

# What's New in HCL RTist 11.1

updated for release 2022.13



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#### Overview

RTist 11.1 is based on Eclipse 2020.06 (4.16)

- HCL RTist is 100% compatible with IBM RSARTE. All features in IBM RSARTE are also present in HCL RTist. However, HCL RTist contains some features that do not exist in IBM RSARTE.
  - Those features are marked in this presentation by



HCL RTist Version: 11.1.0.v20220331\_1741 Release: 2022.13

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Visit https://RTist.hcldoc.com/help/topic/com.ibm.xtools.rsarte.webdoc/users-guide/overview.html





- Compared to RTist 11.0, RTist 11.1 includes new features from 4 quarterly Eclipse releases:
  - 2019.09 (<u>https://www.eclipse.org/eclipse/news/4.13/platform.php</u>)
  - 2019.12 (<u>https://www.eclipse.org/eclipse/news/4.14/platform.php</u>)
  - 2020.03 (<u>https://www.eclipse.org/eclipse/news/4.15/platform.php</u>)
  - 2020.06 (<u>https://www.eclipse.org/eclipse/news/4.16/platform.php</u>)
- For full information about all improvements and changes in these Eclipse releases see the links above

Some highlights are listed in the next few slides...



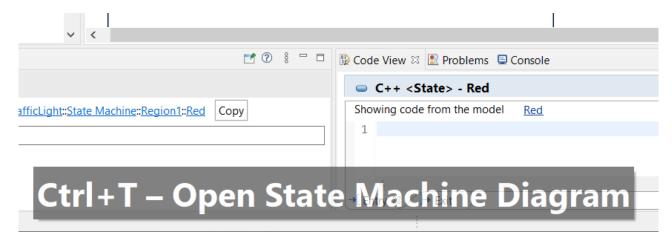
- A new Quick Search dialog allows you to search the files of your workspace faster ("as-you-type")
  - For a similar search experience in model files, use the Find Named Element command instead

	).send	× in: *.cpp
atchi	ng items:	<u>R</u> efresh
ine	Text	Path
154	pedLightControl.walk().send();	TrafficLight.cpp - TrafficLightsTCPAPI_target
51	server. <mark>walk().send(</mark> );	PedLight.cpp - TrafficLightsTCPAPI_target
159	pedLightControl.walk().send();	TrafficLight.cpp - TrafficLightsDemo_target
52	server.walk().send();	PedLight.cpp - TrafficLightsDemo_target
177	pedLightControl.walk().send();	TrafficLight.cpp - TrafficLightsDemoPi_target
52	server. <mark>walk().send(</mark> );	PedLight.cpp - TrafficLightsDemoPi_target
	<pre>f((bool*) rtdata) == true) { pedLightControl.walk().send();</pre>	

- By default at most 99 editors can now be open at the same time
  - Helps keeping the performance good when working with Eclipse for a long time
  - This can be controlled by the preference General Editors Close editors automatically
- Showing key bindings when performing commands
  - New preferences in General Keys

Show key binding when command is invoked
Through keyboard
Through mouse click

This is a good way to learn about key bindings for the commands that are used, and can also help in presentations



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# Eclipse 4.16 (2020.06)

- Quick Access field replaced with toolbar button
  - Takes less space in the toolbar, and instead uses a normal dialog for typing an showing the results
  - Same key binding as before (Ctrl + 3) but the command is now called "Find Actions"
  - The results now also include matching files in the workspace, and text matches in files (requires that Quick Search has been used at least once)

app.tcj		
File content	🔍 `# D:\rsarte	\demos\CompleteTrafficLightDemo09062019\Traff
	🔍 📜 🗧	d from D:\rsarte\demos\CompleteTrafficLightDem
Resources	📲 app.tcjs	
Help	👋 Search ' <b>app</b>	.tcj' in Help

Commands	Preferences (Java > Debug > Heap Walking) - Open the pre
Preferences	Heap Walking - Java/Debug
File content	`pedLightControl.walk().send();` in TrafficLight.cpp
	`server.walk().send();` in PedLight.cpp
Help	😵 Search ' <b>walk()</b> ' in Help



- Show code problems inline
  - Makes errors/warnings more visible and lets you apply quick fixes without having to go to the Problems view
  - Enable this feature in preferences at General Editors Text Editors –
     Show code minings for problem annotations
- ▶ There were several improvements in SWT and GTK
  - The minimal supported GTK version is now 3.20

- New Debug Sources view
  - Shows source files the C++ debugger knows about when debugging an application
  - Useful in particular when the application contains source files that are not present in the Eclipse workspace
  - Source files can be found by searching (filtering) and opened by double-click

🎋 Debug 🛛 🎦 Project Explorer 👘 🗖	Debug Sources & TrafficLight::Sta	🖹 info.txt 🛛 📽 app.tcjs 💽 main() at 0x435 👘 🗖
🖻 🙀 itz 🖇		E E E 🗄 🧇
<ul> <li>executable.EXE [C/C++ Application]</li> <li> <sup>®</sup> executable.EXE [21300]     </li> </ul>	type filter text	
✓	Name	Path ^
main() at 0x435ec3	RTBindingDescriptor.h	D:\rtist11_1\eclipse\rsa_rt\C++\TargetRTS\inclu
> 🧬 Thread #2 0 (Suspended : Container)	RTActorRef.h	D:\rtist11_1\eclipse\rsa_rt\C++\TargetRTS\inclu
>   Thread #3 0 (Suspended : Container)	RTActorClass.h	D:\rtist11_1\eclipse\rsa_rt\C++\TargetRTS\inclu
>   Thread #4 0 (Suspended : Container)	RTActor.inl	D:\rtist11_1\eclipse\rsa_rt\C++\TargetRTS\inclu
>   Thread #5 0 (Suspended : Container)	<ul> <li>eclipse-workspace\rtist-11-1-wksp2\TL_rtist_111_target</li> </ul>	
📕 gdb (8.1)	UnitName.cpp	D:\eclipse-workspace\rtist-11-1-wksp2\TL_rtist_
	TrafficLight.cpp	D:\eclipse-workspace\rtist-11-1-wksp2\TL_rtist_
	LightControl.h	D:\eclipse-workspace\rtist-11-1-wksp2\TL_rtist_
	LightControl.con	Diaclines workenses/rtist 11.1 wken?/TL rtist

- CODAN improvements
  - Several additional checks implemented
- For more information about CDT improvements see <u>https://wiki.eclipse.org/CDT/User/NewIn99</u> <u>https://wiki.eclipse.org/CDT/User/NewIn910</u> <u>https://wiki.eclipse.org/CDT/User/NewIn911</u>

### Newer EGit Version in the EGit Integration

- ▶ The EGit integration in RTist has upgraded EGit from 5.4 to 5.8
  - This is the recommended and latest version for Eclipse 2020.06
- This upgrade provides several new features, performance improvements and bug fixes

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 For detailed information about the changes see <u>https://wiki.eclipse.org/EGit/New and Noteworthy/5.5</u> <u>https://wiki.eclipse.org/EGit/New and Noteworthy/5.6</u> <u>https://wiki.eclipse.org/EGit/New and Noteworthy/5.7</u> <u>https://wiki.eclipse.org/EGit/New and Noteworthy/5.8</u>

- A bash script is now available which helps automating the installation of RTist
  - Download it from the <u>Info Center</u>
  - Works on both Windows and Linux
- ▶ In particular useful for installing RTist 11.1 (due to the requirement of using Java 11 for the installation)

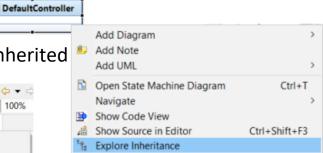
- Choose whether you want to then run RTist with either Java 8 or Java 11
- ▶ For documentation on how to configure and use the script see the <u>Info Center</u>.

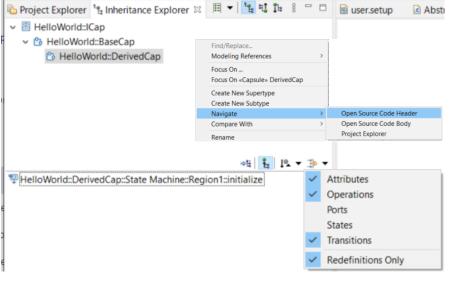


# Improved Inheritance Explorer

- The Inheritance Explorer is now easier to open
  - A new Explore Inheritance command is available in the context menu for elements that can be inherited
  - A new keyboard shortcut has been assigned: Alt + Shift + Q, I
- Both super types (direct and indirect) and sub types (only direct) are now shown initially
  - No longer necessary to manually expand the element to see the sub types
- Support for navigating from Inheritance Explorer to generated C++ code
- Interfaces are now supported in the same way as other types
- Improved the Members view
  - For a capsule, its ports, states and transitions can now be shown
  - Possible to only see the redefinitions (e.g. useful to understand how an inherited capsule or class has been modified)
  - Improved sorting of members according to different criteria

New Window Editor	┃ <b>0 ▼ 9₄ ▼   ⋳                                 </b>		
Appearance	> ss.h 💐 defaultTC.tcjs	Main 🛙	
Show View	> 💷 Bookmarks		
Switch Viewpoint Perspective	Code View     Console	Alt+Shift+Q, C	
Navigation	> The Inheritance Explorer	Alt+Shift+Q, I Alt+Shift+Q, O	
Preferences		Alt+Shift+O.X	





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# **Properties View Improvements**

- The Default Value field now supports multi-line values
  - To create a multi-line default value you still need to use the Code View or Code Editor
  - For editing a multi-line default value you can now use the Properties view, but it's still often more convenient with the Code View or Code Editor

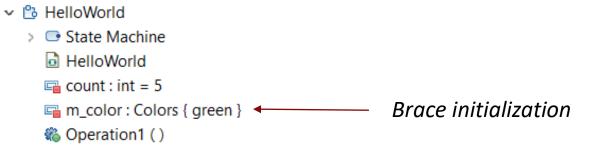
	a : int [3] = { HelloWorld	✓
■ *Properties 🛛	<b>T</b> ? 8 - E	🛚 🚯 Code View 🛛 🛷 Search 🔝 Problem
Attribute>	a	🝙 C++ <attribute> - a</attribute>
General	Qualified Name: <u>HelloWorld</u> :: <u>HelloWorld</u> ::a Copy	Generated source is not found. You shou
Documentation	Name: a	Showing code from the model <u>a</u>
Stereotypes	Visibility: OPublic OPrivate OProtected	2 1,
Constraints		3 2,
Relationships	Modifiers: Static Const ConstExpr	4 3
C++ General	Type: int Select Type Open Type	5 }
C++ Target RTS	Default Value: 2,	3
Advanced	Use Up-Down arrow keys to view other lines	

For quickly viewing a multi-line default value the Properties view can be handy



### **Brace Initialization**

- ▶ For newly created attributes, brace initialization will be selected by default
  - But only if using C++ 11 as code standard
  - Existing attributes are not affected by this change
- The Project Explorer now shows if an attribute uses brace initialization, or some other form of initialization



- When you create a new attribute, and C++ 11 is used, you can now choose if you want to use brace or equal syntax for initialization by directly typing in the Project Explorer
  - When the code standard is older than C++ 11, only the equal syntax is available, and it will map to constructor intialization as before

# **Redefining Non-Virtual Operations**

- When redefining a non-virtual operation in the UI, a warning dialog now appears
- By default the dialog suggests to make the inherited operation virtual, so the model (and generated C++) will become correct

Redefine Operation Warning					
configure: this inherited operation is non-virtual a What do you want to do?	nd should not be redefined.				
Make configure virtual and redefine it					
$\bigcirc$ Leave configure non-virtual and redefine it anyway					
	OK Cancel				

Properties				
🖶 <class> Car</class>				
General		Signature		
Dependencies	8	configure ( )		
			Insert New Operation	
Attributes			Delete from Model	
Operations				
Nested Types			Move Up	
			Move Down	
Documentation	_		Select in Project Explorer	
Stereotypes			· · ·	
Constraints			Redefine Operation	
			Implement Operation	
Relationships			Promote	

# Improvements related to Abstract Classes and Pure Virtual Operations (1/2)

- Previously it was necessary to mark a class (or capsule) as Abstract for the model compiler to treat it like an abstract class
  - A warning would be printed for non-abstract classes containing pure virtual operations 14:08:08 : WARNING : HelloWorld::AbstractClass::pv\_func : This operation cannot be pure-virtual because the owning classifier is not abstract.
- Now the model compiler automatically treats classes with pure virtual operations as abstract
- The Properties View implements the same condition
  - If a class (or capsule) is not marked as abstract, but has pure virtual or interface operations (locally defined or inherited), the Abstract checkbox is automatically set (and made read-only)

A tooltip explains why the class (or capsule) is

Toperties 🛛 🖸 🕈 🖬						
Class> AbstractClass						
General	Qualified N	lame: HelloWorld::AbstractClass Copy				
Dependencies	Name:	AbstractClass				
Attributes	Visibility:	Public      Private      Protected				
Operations						
Nested Types	Modifiers:	Modifiers: Abstract Final				
Documentation		Abstract due to the pure virtual operation HelloWorld::AbstractClass::pv_func ( )				

considered abstract (useful in case it's abstract because you forgot to redefine or implement an operation)

# Improvements related to Abstract Classes and Pure Virtual Operations (2/2)

- Note that automatic computation of the Abstract property is based on comparing the signature of operations. If operations in the inheritance hierarchy have parameters with inconsistent use of types (e.g. mixed use of regular types, typedefs, type aliases or macros) then the automatic computation may fail.
- A new preference RealTime Development Build/Transformations C++ Automatically compute if a class or capsule is abstract controls if the Abstract property should be automatically computed (by default it's not)
  - Note that this preference applies both for code generation and the Properties view
- The Project Explorer and diagrams now show <u>all</u> abstract classes and pure virtual operations in italics

AbstractClass \$\$\$ pv_func () = 0		AbstractClass
	Signature:	pv_func ( )= 0

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▶ Also, pure virtual operations now have "= 0" appended to their signatures



### **Project Explorer Improvements**

- The Project Explorer can now show template information after the name of an element that has template parameters
  - Makes it easier to see if an element is a template without having to expand it in the Project Explorer, or look in the Properties view
  - A new preference RealTime Development Project Explorer Show Template Parameters in Labels controls what to show

Show Template Parameters in Labels	Show full template parameter list $\sim$
	Do not show
	Show existence of template parameters
	Show full template parameter list

✓ □ List
 Itypename Element
 Itypename size : unsigned int

Do not show template parameters Show existance of template parameters

✓ □ List<typename Element, size : unsigned int>
 № typename Element
 № size : unsigned int

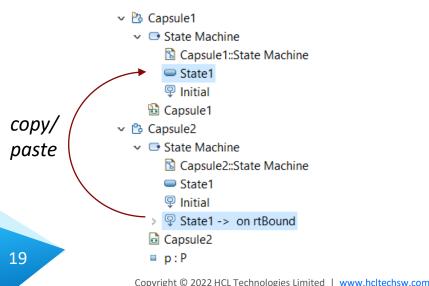
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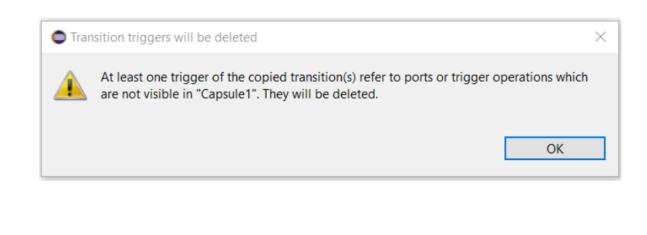
Show full template parameter list

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# Copy/Paste of Transitions in the Project Explorer

- You can now copy a transition and paste it on a target state using the Project Explorer
  - More convenient than creating a new transition and then copy/paste the effect and guard code (and possibly other transition properties) separately
  - Works for transitions in both capsule and passive class state machines
  - The pasted transition will initially become a self-transition and can be rerouted later if needed
- If ports or trigger operations referenced by triggers of the copied transition are not available in the target context, a dialog will inform that such triggers will be deleted





# **Automatic Creation of Fragment Files**

- A new preference was added for automatically creating fragment files for newly created model elements
  - Modeling Automatically create fragment files

Library Hover
 Modeling
 Model Validation
 Mylyn
 Oomph
 Plug-in Developm
 Save artifacts to newer version without prompting
 Migrate default appearance properties
 Show Reload Model dialog only if save is needed
 Fragment file name pattern \$(NAME)\$(OPT\_INDEX)
 Automatically create fragment files

- Setting this preference can be useful if you prefer to always create fully fragmented models
- Note that
  - for state machines no fragment files will be automatically created,
  - fragment file creation cannot be undone,
  - fragment files are not automatically renamed when you rename the element stored in it (use the command Refactor – Rename file if you want to rename the fragment file)



# Search Filtering

- ▶ It's now possible to filter search results using Boolean operators NOT (!) and AND (&&)
  - Useful if a search returns too many matches
  - Use a filter on the form

!A && !B && ... !X to hide matches where certain words <u>are</u> <u>not</u> present

- Use a filter on the form
   A && B && ... X to only show matches where certain words <u>are</u> present
- ...or any combination, where some words are present and others not
- Enclose the filter string in double quotes to apply the filter verbatimly
  - Needed if the filter string contains the characters ! or &&

	🔗 Search 🛛	😳 Code View	🕄 Problems  트 Co	onsole 🗏	Progress	
'results' (verbatim, case insensitive): Showing 5 matches in Workspace.						
l	Match = !are	&& lencode		≱ 🗙	Kind	
	cout << "I	No <b>results</b> found	!";		Code (Entry o	f State)
	→ cout <<	"Search results:	<pre> &lt; results.c_str()</pre>	<< endl;	Code (Effect o	of Tra
	→ cout <<	"Search results:"	<< results.c_str()	<< endl;	Code (Effect o	of Tra
	=cout << "	Results found "	<< results.c_str() <<	endl;	Code (Entry o	f State)
	=cout << "	Results found " <	< results.c_str() <<	endl;	Code (Entry o	f State)

🔗 Search 🛛 🔀 Code View 🖹 Prob	lems 🗏 Console 🖷 Progress			
'results' (verbatim, case insensitive): Showing 2 matches in Workspace.				
Match = "!" Kind				
cout << "No results found!";	Code (Entry of State)			
msg = "Results warning!";	Code (Exit of State)			

# **Enums with Operations**

- Enumerations can now have operations
  - Create them as usual with Add UML Operation

✓ I Colors				ээ кнтуретнусатте			
	Add UML	>		Enumeration Literal	1		
GREEN	Add Diagram	>	۲	Operation	au		

- Such operations will be translated to global functions
  - C++ enums cannot have member functions, but it's sometimes useful to have functions that operate on or return enum literals
  - Using global functions can then be an alternative to wrapping the enum inside a class

v 🖭 Col	ors					
I RED						
I GREEN						
> 🍪 🤆	getDefault ( ) : Colors					
B# 10-	"Drimitive Dataturas)					
🔲 Properties 🛛						
<pre>% <operation> getDefault ( )</operation></pre>						
General						
Parameters	Kind:	🔿 friend 🖲 global 🔾 member				

This works the same both for scoped and non-scoped enumerations

### Generic Type Descriptors

- The model compiler now supports generating type descriptors for type aliases with template parameters
  - For example: template<typename T, unsigned int N > using StdArray = std::array<T, N>;
  - If type descriptor functions are defined for the type alias, they will be generated as template functions with the same template parameters
  - Allows to implement generic type descriptors that work for all (or many) instantiations of the template
  - A new RTObject\_class::fromType<T>() template function can be used for looking up the type descriptor of a type at compile time. Useful for example when implementing generic encode or decode functions. Specialize it for the types that you use (specializations for built-in types are available in the TargetRTS). For example:
     template <> inline const RTObject\_class\* RTObject\_class::fromType<RTString>() {
     return &RTType\_RTString;
     }
- You can specify a unique name for the type descriptor of a specific template instantiation
  - For example: template <> const char\* RTName\_StdArray<StdString, 4>::name = "StdArray<StdString, 4>";
  - The TargetRTS now prints a warning if two type descriptors with the same name exists. Helps troubleshooting missing template specializations for the name attribute.

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# Custom Capsule Constructors

- It's now possible to create custom constructors for capsules
- Each capsule constructor has two mandatory parameters:
  - rtg\_rts Controller (i.e. thread) that will run the created capsule instance

Add UML

- rtg\_ref Capsule part where the created capsule instance will be inserted
- In addition you can add any number of user-defined parameters
- This feature makes it possible to pass initialization data to a capsule instance already when it's created
  - Previously this could only be done by sending such data with the initialization event (which is not possible for fixed capsule parts)
  - Custom capsule constructors work for all capsules regardless of the capsule part they are incarnated into

				Getter/Setter
			_	
v	്ര	А		
	>	•	State Machine	
		o	A	
			val : unsigned int = 0	
	v	86	A()	
			rtg_rts : RTController * rtg ref : RTActorRef *	
			🔅 rtg_ref:RTActorRef*	

p: unsigned int

Attribute

Operation

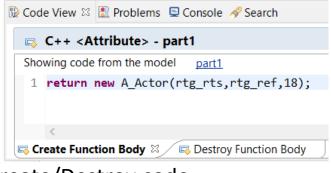
Special Operation

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Constructor

# Capsule Factories (1/2)

- The concept of a <u>capsule factory</u> was introduced to allow incarnating capsules with custom constructors
  - Specifies how a capsule instance is created and destroyed
  - Can be provided in various ways (in a hierarchical manner)
- New capsule factory code snippets for capsule parts
  - All capsule instances incarnated in that capsule part will use the specified Create/Destroy code
- New capsule factory property for capsule parts
  - Will be used if no Create/Destroy code is provided for that capsule part
- New capsule factory property in the TC
  - Will be used if none of the above are provided
  - Allows specifying a default (global) capsule factory
  - A variable \$(CAPSULE\_CLASS) can be used in this TC property
     Capsule Factory:
     (expands to the name of the class that is generated from the type of the capsule part)



■ Properties \u00e4				
🗟 <attribute></attribute>				
General				
Documentation		<		
Stereotypes	Create Function Body:			
Constraints		1		
Relationships				
C++ General		<		
C++ Target RTS	Capsule Factory:	&CapsuleFactory::factory1		
Capsule Factory:	&GlobalCapsuleFactory<	(CAPSULE_CLASS)>::factory2		

# Capsule Factories (2/2)

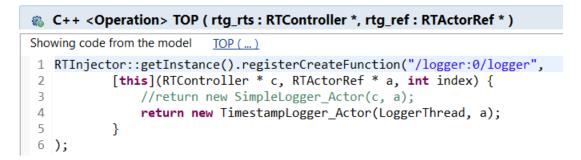
- For optional capsule parts, it's also possible to provide the capsule factory using a new TargetRTS function RTFrame::incarnateCustom()
  RTActorId incarnateCustom(RTActorRef & cp, CarnateCustom)
  - In this case, only the Create code can be provided (the regular delete operator will be used for destroying such capsule instances)
  - Example usage:

```
RTActorId id = frame.incarnateCustom(part1,
RTActorFactory([this](RTController * c, RTActorRef * a, int index) {
    return new A_Actor(c, a, 444); // User-defined constructor
})
);
```

- ▶ If multiple capsule factories are provided, they will be picked in this priority order:
  - 1. The capsule factory provided in a call to RTFrame::incarnateCustom()
  - 2. The capsule factory specified by means of Create and/or Destroy code snippets on a capsule part
  - 3. The capsule factory specified by the "Capsule Factory" property on a capsule part
  - 4. The capsule factory specified in the "Capsule Factory" property on the TC

RTActorId incarnateCustom( RTActorRef & cp, RTActorFactory& factory, int index = -1);

- A capsule normally depends on many things at run-time for its execution
  - Examples: Other capsules typing its capsule parts, the thread that will run the capsule, initialization data to pass to the capsule constructor, etc.
- Spreading out such dependencies in a hard-coded way in an application can make it hard to change them to configure different variants of an application
  - E.g. mocking out dependent capsules when unit testing a capsule
- The TargetRTS now provides a new dependency injection service realized by the RTInjector class
  - Register the dependencies to configure the application (typically early, e.g. in the top capsule constructor)
  - A create function can be registered for a capsule part (identified by its qualified path name)
  - A capsule factory can delegate to RTInjector::create() for creating capsule instances
  - If necessary, registered dependencies can be changed at run-time



# Moving Event Data (1/2)

- The data of an event can now be moved instead of copied when sent between two capsules MyClass mc; thePort.theEvent(mc).send(); // Send by copy thePort.theEvent(std::move(mc)).send(); // Send by move
- This requires that the event data type is movable, which can be accomplished
  - by having a move constructor, and/or
  - by having a move function defined in the type descriptor
- The move function is a new type descriptor function (describing how to move data from a source to a target object)
  - If the target object has a move constructor, a typical implementation is to invoke it (the model compiler can automatically generate such an implementation)
  - Contrary to other type descriptor functions, the move function is optional (you only need to implement it if the type needs to be movable)
  - If no move function is defined, and an attempt is made to move an object, it will instead be copied

Properties		r 🕐 🕅	
Class> StdS	tring (typedef of std::st	ing)	
 Operations			_
Nested Types	Copy Function Body:	Edit	
		<pre>1 target = new (target) std::string(*source);</pre>	
Documentation		×	
Stereotypes		< >	
Constraints	Move Function Body:	Edit	
Relationships	more runction bouy.	<pre>1 target = new (target) std::string(std::move(*source)); ^</pre>	
C++ General		2	
C++ Target RTS		▼ maua⊑una€auntiii	
Advanced			

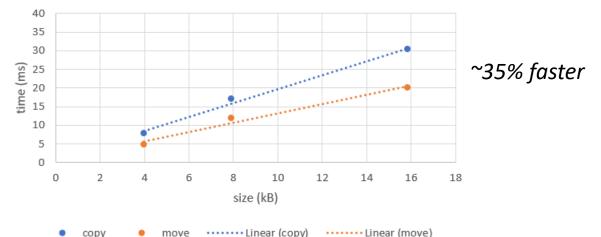
# Moving Event Data (2/2)

- You can also move the data from a received message into, for example, a capsule attribute someAttr = std::move(\*rtdata); // Avoid copying the message data object
- This requires that rtdata is declared as non-const (so the move constructor or move assignment operator will be invoked)
  - Can be accomplished by a new transition property

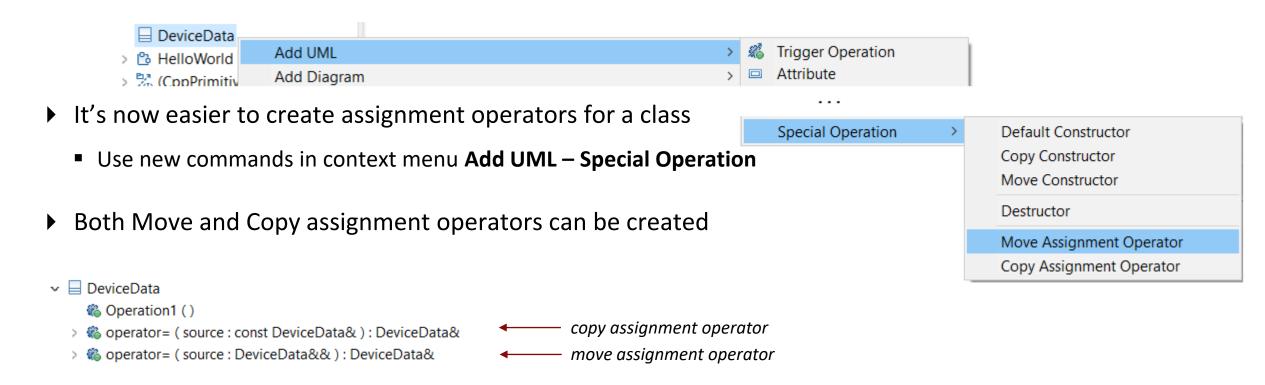
🔲 Properties 🛛					
♀ <transition> t1</transition>					
General Qualified Name: <u>Move function 2::Inner::State Machine::t1</u> Copy					
Triggers	Name:	t1			
Documentation	Kind:	External	$\checkmark$		
Stereotypes Const rtdata parameter					
Constraints					

- Moving instead of copying event data can improve application performance if
  - the data object is big, and/or
  - the data object is sent many times

Sending a data object 100 times



### **Creation of Assignment Operators**



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### More C++ Language Standards

- The preference RealTime Development Build/Transformations C++ C++ Code Standard can now be set to more C++ language standards
- The corresponding model compiler argument --codeStandard was extended too
- ▶ The default language standard is now set to C++ 17
  - Matches the compilers used for building the precompiled versions of the TargetRTS
- Explicitly setting which language standard to use makes it possible for the model compiler to issue a warning if a C++ language construct is used that is not supported in the selected language version

C++ code standard	C++ 17 ~	
Code compliance	C++ 20 C++ 17	
Clang-Tidy	C++ 14	
Make options	C++ 11 Older than C++ 11	



# Marking Elements as Deprecated

- Many elements can now be marked as deprecated using new widgets in the C++ General property tab
  - Optionally, a deprecation message can also be provided (for example to suggest an alternative element to use instead)

Ko 1	resizeFields ( )					
	(BaseCap)	~				
<		>	<			
■ *Properties 🛛				7	8 🗆	
<pre>% &lt; Operation</pre>	> resizeFields ( )					
General	_	accuration and actimition				^
Parameters	✓ Deprecated					
Exceptions	Message:	Deprecated since version	2.19, use recomputeFields() instead			

- A deprecated element is allowed to be used, but its usage is discouraged
  - The C++ compiler will print the deprecation message if it detects that the deprecated element is used

../DerivedCap.cpp:36:14: warning: 'void DerivedCap\_Actor::resizeFields()' is deprecated: Deprecated since version 2.19, use recomputeFields() instead [Wdeprecated-declarations]
resizeFields();

- ▶ This feature requires C++ 14 or later
  - If the C++ Code Standard preference is older than C++ 14, the model compiler will print a warning

10:01:25 : WARNING : CPPModel::DerivedCap::resizeFields : Marking an element as deprecated requires C++ 14 or later.



# **Code Compliance**

- A new preference was introduced to let the model compiler generate code according to certain code compliance rules
- Support for these Clang-Tidy rules are implemented:
  - cppcoreguidelines-pro-type-static-cast-downcast
     Suppress warnings for use of static\_cast to downcast
     event data in transition functions

type filter text	C++
<ul> <li>&gt; Oomph</li> <li>&gt; Plug-in Developm</li> <li>&gt; RealTime Develop</li> <li>&gt; Build/Transforn</li> <li>C++</li> <li>Code Editing</li> <li></li> </ul>	C++ code standard C++ 11 ~ Code compliance Clang-Tidy Make options
? 🗠 🗹 🔘	

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```
transition2_t1( static_cast< const bool * > ( msg->data ), static_cast< P::Base * > ( msg->sap()
/* NOLINT(cppcoreguidelines-pro-type-static-cast-downcast) */ ) );
```

#### misc-unused-parameters

Suppress warnings for named function parameters that are not used in the function body

static void rtg\_B\_init(const RTObject\_class \* type /\* NOLINT(misc-unused-parameters) \*/, B \* target );

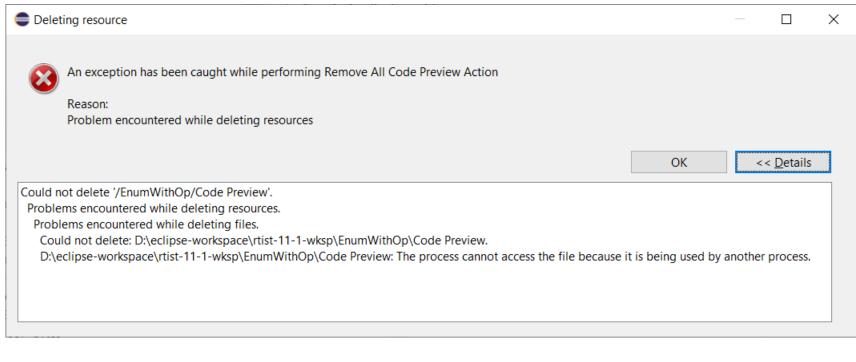
bugprone-sizeof-expression

Suppress warnings for computing the size of a pointer type using sizeof

, sizeof( SomeClassPtr ) /\* NOLINT(bugprone-sizeof-expression) \*/

# Error Message when Failing to Delete Files or Folders

- Certain commands in RTist involve deletion of files and/or folders
  - Cleaning a TC
  - Removing code preview
  - ...etc
- Now, if the required files or folders cannot be deleted, a clear error message is shown
  - Previously there would be a silent failure in such situations which could be hard to understand the reason for



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The new message is identical to what Eclipse would show if you directly try to remove the files/folders from the Project Explorer. Click the **Details** button to see exactly which file or folder that couldn't be deleted, and why.

# More Flexible Model References in Transformation Configurations

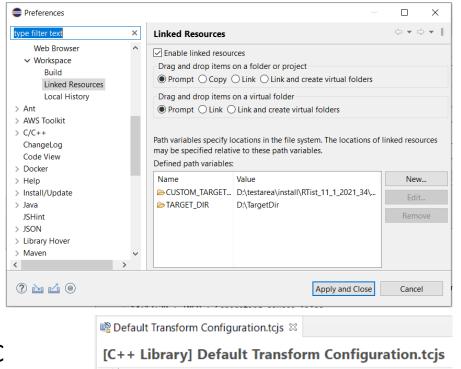
- ▶ A TC references model elements by means of URIs (e.g. list of source elements, top capsule etc)
- Such URIs can now be relative, and use qualified names instead of unique IDs to identify the element
  - Makes it easier to reuse a TC (e.g. by copy/paste) in different projects
- New preferences control how new URIs will created:
   RealTime Development Transformation Configuration Editor Model References

Model References	
Use relative URIs to reference model elements	
Use fully qualified names in model element URI references (instead of xmi id)	
Example:	
/MyModel.emx?MyModel::MyCapsule	

# Support for Path Variables in Transformation Configurations

- Path variables can now be used in certain TC properties
  - Useful for those TC properties that specify a path
  - Define path variables in Preferences at General Workspace Linked Resources
  - This can be an alternative to using string substitutions (Run/Debug String Substitutions) or environment variables in order to have a more generic TC (a path variable takes precedence over other kinds of variables, if the same variable name is used).
- The model compiler now prints a warning if a variable used in a TC property cannot be resolved

```
WARNING : Cannot resolve variable '$(TARGET_DIR)' in
'Location' property:'$(TARGET_DIR)'
```



- Target ✓ Automatically create a	and upd	ate target project			
Workspace output path:	/Temp	late_target			
Use default location					
Location:	\$(TARC	SET_DIR)			
Documentation					
in References Code Ger	peration	Target Configuration	Threads	Code	

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# New TargetRTS Flag for Faster Plugin Capsule Part Imports

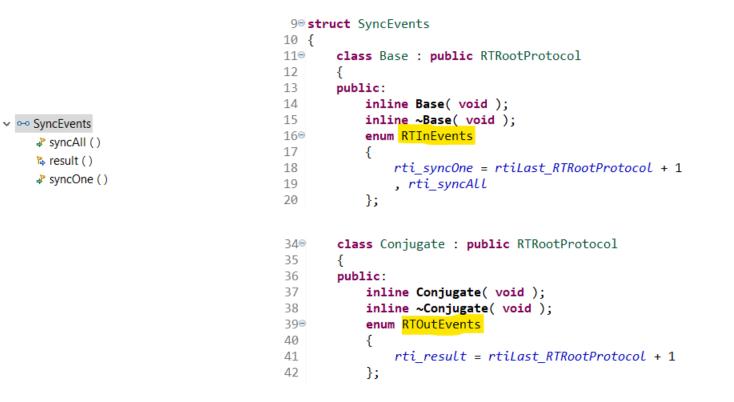
- When importing a capsule instance into a plugin capsule part a run-time check RTActor::isReferencedBy() is performed to ensure there are no cycles in the reference graph
- This run-time check can sometimes take too much time
- The TargetRTS now provides a new compile flag RTIMPORT\_ISREFERENCEDBY\_CHECK for disabling this run-time check

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Set it to 0 in RTLibSet.h or RTTarget.h to disable the check

### Named Event Enumerations in Generated Code

- Previously the enums generated for protocol classes were anonymous
- Now they are named "RTInEvents" and "RTOutEvents" respectively
  - Makes it possible to reference them from other code



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#### Unit Testing of Capsules using the Mocha Framework (1/3)

- Mocha is a popular JavaScript framework for testing asynchronous applications
- It's now possible to use Mocha also for unit testing capsules
  - Provided by a new component that can be selected when installing
  - Note that it depends on NodePlus

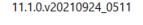
> ModePlus
 > ModePlus
 > RTist Core

Image: Second state
 Image: Second state<

OneTest Embedded Integration

- To create a Mocha unit test for a capsule, invoke the new context menu command Add Unit Test
  - PushButton
     Server
     TLSystem
     TrafficLight
     TrafficLight
     HttpServerInternation
     Coop Structure Diagram









# Unit Testing of Capsules using the Mocha Framework (2/3)



- The Add Unit Test command creates everything necessary for writing a unit test for the capsule
  - A test driver model where all service ports of the capsule under test ("cut") are connected to similar but conjugated ports of a test probe capsule
  - A TC for building the test driver model into an executable that uses the TcpServer library for exposing all test probe ports to the Mocha test script
  - A Node.js project with a Mocha test script ready to implement the unit test

) ed	<ul> <li>test_TrafficLight</li> <li>Main</li> <li>TestContainer</li> <li>TestProbe</li> </ul>	
contro	cut : TrafficLight of pedLightControl~	eð server
cont	ontrol~ test_pedLightControl rol I testProbe : TestProbe	test_server~

- Iransformation Configurations
- > 🗟 «C++ Executable» app\_win
- > 🗟 «C++ Executable» TrafficLight\_UnitTests
- > 🛋 JavaScript Resources
- 🗸 🗁 test
  - tests\_TrafficLight.js
- D package.json

Add Unit Test – D ×					
Enter Test Case Details					
Test Case					
Name	tests_TrafficLight				
Description	should initially be in Red state				$\hat{}$
Test Driver					
Package Name	test_TrafficLight				
Port	2234				
Transformation Configuration					
Name	TrafficLight_UnitTests				
Output Path	TrafficLight_UnitTests_target				
Test Application					
Host	localhost				
Port	9911				
?	[	<u>F</u> inish		Can	cel

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# Unit Testing of Capsules using the Mocha Framework (3/3)



- The unit test can be executed right away
  - Build the test driver TC (only needed the first time, and whenever you change the capsule under test)
  - Install the Node.js dependencies for the JavaScript project (right-click on the project and do Run As – npm install (only needed the first time – it is assume you already have installed Mocha on the machine)
  - Run the testcase by right-click on the .js file and do
     Run As JavaScript Unit Test

🖪 te	sts_TrafficLight.js 🛛	TestContainer TrafficLight_UnitTests.tcjs				
1	<pre>1 var assert = require('assert');</pre>					
2	<pre>2 describe('TrafficLight', function() {</pre>					
3	<pre>3 it('should initially be in Red state', function() {</pre>					
4	<pre>4 this.timeout(15000);</pre>					
5	<pre>const testProbe = require ('rt-test-probe')('localhost', 9911);</pre>					
6	<pre>return testProbe.startListenForEvents(2234)</pre>					
7	.then((data) => {					
8	3 // TODO: Implement test here					
9	})					
10	$finally(() \Rightarrow \{$					
11	<pre>testProbe.stopListenForEvents();</pre>					
12	});					
13	});					
14	});					

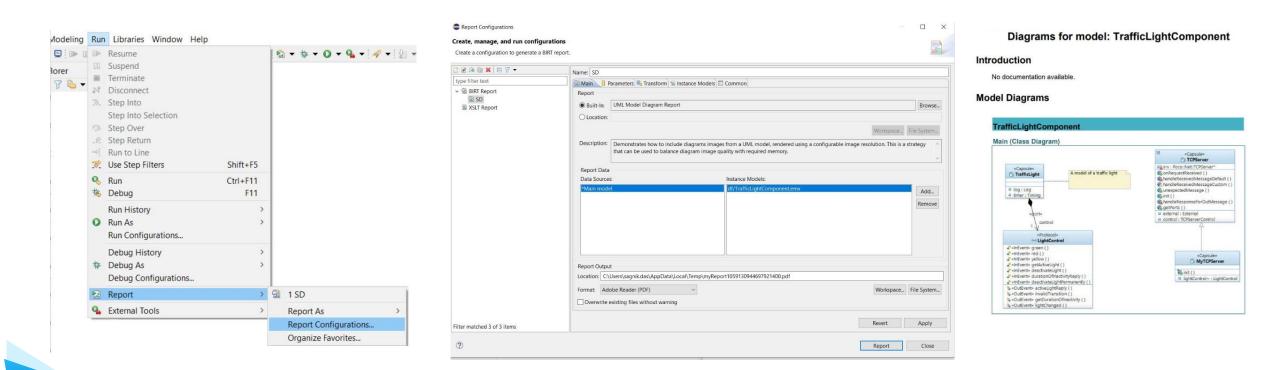
The test execution result is shown in the JavaScript Unit Test view

Runs: 1/1 Errors: 0 Failures: 0	
✓ In TrafficLight	асе



# **Reporting with BIRT**

- Create reports that include information from an RTist model
  - Same capabilities as in RTist 10.3, but now adapted for recent Eclipse versions (supports RTist 11.0 and RTist 11.1)
  - Delivered as a separate update site on <u>our InfoCenter</u>. Installation instructions are included in the ZIP file.



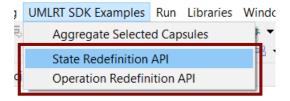
### Java API Improvements

- A new method for programmatically redefining an inherited operation was added
  - com.ibm.xtools.uml.redefinition.RedefFactory.getOperationRedefinition()
- Read more about this new method in the Help (RTist Java APIs Reference API Reference UML Modeling Layer)

Search: Go Sco	<u>pe:</u>	All topics
Contents 👜 🗸 🖗 🖻		今 今 🏠 比 🍕 📲
▣ ♥ GProf User Guide ▣ ♥ Libhover Developer's Guide	^	RTist Java APIs > RTist Modeling Platform Developer's Guide > Reference
🗉 🧇 Meson Plug-in User Guide		RTist Modeling Platform API Reference
<ul> <li>Mylyn WikiText Documentation</li> <li>Oomph P2 Management Documentation</li> </ul>		The HCL RTist developer products provide public API for creating and modifying UML models and diagrams.
<ul> <li>I Image Oomph Setup Documentation</li> <li>Image Profiling Framework User Guide</li> <li>Image Image Of Imag</li></ul>		The API for modeling is logically divided into functional subsystems. The main classes for creating or opening UML models are defined in the UML Modeler subsystem, and the remaining subsystems provide the underlying modeling support. Some of these subsystems are determined as a determined by a determi
RTist Modeling Platform Developer's Guide Programmer's Guide	ł	subsystems may not be available in the current product but may be available as a downloadable add-on. The subsystems for the RTist Modeling Platform are:
<ul> <li>Tutorials</li> <li>Examples Guide</li> <li>Reference</li> <li>API Reference</li> </ul>		<ul> <li><u>UML Modeler</u></li> <li><u>UML Modeling Layer</u></li> <li><u>Domain Modeling Layer</u></li> <li><u>RichText Framework</u></li> </ul>
<ul> <li>Ⅲ Ⅲ Extension Points Reference</li> <li>Ⅲ Ⅲ Other Reference Information</li> <li>Ⅲ Ⅲ RTist Transformation Developer's Guide</li> </ul>		© Copyright HCL, IBM and others 2004, 2021

# UML RT SDK Sample

- The sample was updated with two new commands showing how to redefine states and operations using existing and new Java APIs
  - Also shows how to create generalizations programmatically





Relationary BEYOND THE CONTRACT

**\$7** BILLION ENTERPRISE | **110,000** IDEAPRENEURS | **31** COUNTRIES

